## #4 Into Orbit - Drivetrain and Chassis Specification



- 1. Evaluate all the Launch Planning Sheets from the team to build a drivetrain and chassis to meet the requirements.
- 2. Draw a 2D model (or 3D model).

## **Output Ports:**

А	В	С	D		

## Input Ports:

1	2	3	4

<b></b>					
Chassis Size:	Width	Length:			
Large motor: $A E'' \times 1 E''$					
Medium motor: 3" x 1"	Height:	Clearance:			
Movement/Turns:	Forward Drive Rear Drive	Importance: 🗆 Straight 🗆 Turns			
	Distance (speed) Accuracy (slow)				
	Size of the driving wheels: Radius: Width:				
	Size of the castor wheels: Radius:	Width:			
	Motor wheels Diameter:	Width:			
Sensors:	Color Sensor - 1 or 2	🗆 Gyro Sensor			
Color Sensor:					
0.75″ x 0.75″	Location:	Location:			
Ultrasonic Sensor:					
2" x 1.75" x 1.25"					
Touch/Gyro Sensor:					
0.75″ x 0.75″	Location:	Location:			
Medium Motors:	Location:	Location:			
	Attachments:	Attachments			
Large Motors:	Location:	Location:			
	Attachments:	Attachments:			
Walls:	Front:	Right Side:			
	Width: Height:	Width: Height:			
	Attachments:	Attachments:			
	Back:	Left Side:			
	Width: Height:	Width: Height:			
	Attachments:	Attachments:			

Attachment #1:	Name:			
	Medium motor:	large motor:	Dassiva	
	Length:	Width:	Height:	
A 1	Location:			
Attachment #2:	Name:			
	Medium motor:	Large motor:	Passive:	
	Length:	Width:	Height:	
	Location:			
Attachment #3:	Name:			
	Medium motor:	Large motor:	Passive:	
	Length:	Width:	Height:	
	Location:			
Attachment #4:	Name:			
	Medium motor:	Large motor:	Passive:	
	Length:	Width:	Height:	
	Location:			
Attachment #5:	Name:			
	Medium motor:	Large motor:	Passive:	
	Length:	Width:	Height:	
	Location:			
Attachment #6:	Name:			
	Medium motor:	Large motor:	Passive:	
	Length:	Width:	Height:	
	Location:			

Note: